AISB2010 Convention • 29th March-1st April 2010

Programme Overview

	MONDAY 29 th March	TUESDAY 30th March	WEDNESDAY 31st March	THURSDAY 1st April		
	Hugh Aston Building – De Montfort University					
8:00						
8:30	OPENING SESSION Dean of Faculty of Technology, Chair of AISB, Chair of AISB2010 Convention	Regis	tration			
9:00	Sessions	Sessions	Sessions	Sessions		
10:30	Coffee Break	Coffee Break	Coffee Break	Coffee Break		
11:00	Sessions	Sessions	Sessions	Sessions		
		Food available	EYNOTE TALK from 12:00-15:00 s 13:00-14:00			
	Numbers to die 4 Prof. Harold Thimbleby	Artificial ethical intelligence: technical, conceptual and ethical challenges Prof Steve Torrance	From biology to robots: the RobotCub project Dr. Giorgio Metta	AISB annual general meeting		
	Hugh Aston Building – De Montfort University					
14:00	Sessions	Sessions	Sessions	Sessions		
15:30	Coffee Break	Coffee Break	Coffee Break	Coffee Break		
16:00	Sessions	Sessions	Sessions	Sessions		
19:00	Movie	Movie	Convention Dinner Movie	Movie		

Room Assignments

	MONDAY 29th March	TUESDAY 30th March	WEDNESDAY 31st March	THURSDAY 1st April
Room 1	Mathematical Cognition	Mathematical Cognition	Biologically inspired Al vs Al inspired Biology	Biologically inspired Al vs Al inspired Biology
Room 2	Human Memory for Artificial Agents		New Frontiers in Human-Robot Interaction	New Frontiers in Human-Robot Interaction
Room 3		Al and Games		
Room 4	Social Network Analysis and Norms for MAS	Social Network Analysis and Norms for MAS	Matching and Meaning	Matching and Meaning
Room 5		Swarm Intelligence Algorithms and Applications	Evolving Intelligent Systems	
Room 6	Linguistic and Cognitive Approaches To Dialogue Agents			
Room 7	Towards a Comprehensive Intelligence Test	Towards a Comprehensive Intelligence Test		

Evening Events — Al-Inspired Film Festival in conjunction with Phoenix Square					
	MONDAY 29 th March	TUESDAY 30 th March	WEDNESDAY 31st March	THURSDAY 1st April	
19:00 -	Al: Artificial Intelligence (12)	Breaking the Code (12A)	Moon (15)	Bicentennial Man (to be confirmed)	

Optional movie, for all conference participants, at Phoenix Square in the Leicester Cultural Quarter (http://www.phoenix.org.uk/)

Tickets: £4.80 (with DMU discount) and £3.80 (on the presentation of AISB2010 delegates badge)

There are limited reserved tickets for convention attendees, you can reserve your ticket over the phone and collect at the reception desk on presentation of your convention badge for discount.

	Room 1: Mathematical Practice and Cognition	Room 2: Human Memory for Artificial Agents	Room 4: Social Network Analysis and Norms for MAS	Room 6: Linguistic and Cognitive Approaches To Dialogue Agents	Room 7: Towards a Comprehensive Intelligence Test
8:00			Registration		
8:30		Dean of Faculty of	OPENING SESSION (THEATRE ROOM) Technology, Chair of AISB, Chair of AI	SB2010 Convention	
9:00	Welcome 9:00-10:00 — Invited talk Little green men from Mars and other thought experiments in philosophy of mathematics Alexandre Borovik 10:00-10:30 If learning Math requires a teacher, where did the first teachers come from? Aaron Sloman	9:00-9:10 Short introduction MEMORY FOR VIRTUAL AGENTS AND ROBOTS 9:10-9:50 Timing in episodic memory: virtual characters in action Ondřej Burkert, Cyril Brom, Rudolf Kadlec and Jiří Lukavský 9:50-10:30 Extending Soar with dissociated symbolic memories Nate Derbinsky and John E. Laird	Introduction to SNAMAS 2010 What is power? Articulating perspectives from sociology, multiagents systems and network analysis M. Mailliard Optimizing the core computation with social networks L. Sauro and S. Villata	DIALOG SYSTEMS AND HCI/HRI ARCHITECTURES 9:00-9:30 An emotional humanoid partner S.M. Anzalone, F. Cinquegrani, R. Sorbello, A. Chella 9:30-10:00 Learning a grounded language model for human-robot interaction Antonio Chella, Haris Dindo and Daniele Zambuto 10:00-10:15 Facial expressions for communicating user feedback Savandie Abeyratna, Galina Paramei, Hissam Tawfik, Rentian Huang 10:15-10:30 Forgetful and emotional: recent progress in development of dynamic memory management system for conversational agents Michal Ptaszynski, Pawel Dybala, Rafal Rzepka, Kenji Araki	9:00-9:30 Connecting the dots my own way: Sphex-test and flexibility in artificial cognitive agents Juan Camilo Espejo-Serna 9:30-10:00 Causal and communal factors in a comprehensive test of intelligence Paul Schweizer 10:00-10:30 Qualia Turing Test - Designing a test for the phenomenal mind Alessio Plebe and Pietro Perconti
10:30			Coffee Break		

	Room 1: Mathematical Practice and Cognition	Room 2: Human Memory for Artificial Agents	Room 4: Social Network Analysis and Norms for MAS	Room 6: Linguistic and Cognitive Approaches To Dialogue Agents	Room 7: Towards a Comprehensive Intelligence Test
11:00	11:00-11:30 Geometric proof checking with Diagrams John Mumma 11:30-12:00 Interpreting Naproche-An algorithmical approach to the derivation-indicator view Merlin Carl and Prof. Dr. Peter Koepke 12:00-12:20 Applying the GC Combined Reasoning Framework to Mathematical Discovery John Charnley	MEMORY FOR VIRTUAL AGENTS AND ROBOTS (CONT'D) 11:00-11:40 Short- and long-term adaptation of visual place memories for mobile robots Feras Dayoub, Tom Duckett and Grzegorz Cielniak 11:40-12:00 I can (almost) remember what you are doing: from actions to tasks Rudolf Kadlec and Cyril Brom 12:00-12:20 An object-based memory for supporting attentive virtual agents Christopher Peters	11:00-12:30 — Invited talk Bruce Edmonds	LANGUAGE CREATIVITY, HUMOR AND METAPHORS 11:00-11:30 Associative text categorisation rules pruning method Hussein Mansour, Wa'el Musa Hadi, Lee MCclusky, Fadi Thabtah 11:30-12:00 Metaphorical and contextual affect detection in an intelligent agent Li Zhang 12:00-12:15 Chain of events: multi-stage approach to humor and emotions in HCI Pawel Dybala, Michal Ptaszynski, Rafal Rzepka, Kenji Araki 12:15-12:30 Evaluation of a humor generation system by real world application with ¥500,000 to win Jonas Sjobergh, Kenji Araki	11:00-11:30 Considering social and emotional artificial intelligence Marc Schroeder and Gary McKeown 11:30-12:00 Actions and observations - demonstrating aspects of understanding in a simple world Chris White and David Bell 12:00-12:30 Towards a staged developmental intelligence test for machines Ed Keedwell
12:30			Lunch + Keynote talk (at Phoenix Square)		

	Room 1: Mathematical Practice and Cognition	Room 2: Human Memory for Artificial Agents	Room 4: Social Network Analysis and Norms for MAS	Room 6: Linguistic and Cognitive Approaches To Dialogue Agents	Room 7: Towards a Comprehensive Intelligence Test
14:00	Dynamism in mathematical thought (where there shouldn't be any): A study of gesture in the production of mathematical proof Tyler Marghetis, Rafael Núñez 14:30-14:50 The body in Renaissance arithmetic: from mnemonics to embodied cognition Albrecht Heeffer 14:50-15:10 Origins of spatial-numerical bias Martin Fischer 15:10-15:30 Interpretation is an action: understanding diagrams by manipulating them Valeria Giardino	MEMORY FOR VIRTUAL AGENTS AND ROBOTS (CONT'D) 14:00-14:30 Human-like memory systems for interactive robots: desiderata and two case studies utilizing grounded situation models and online social networking Nikolaos Mavridis and Michael Petychakis MEMORY MODELS AND ALGORITHMS 14:30-15:10 Comparing forgetting algorithms for artificial episodic memory systems Andrew Nuxoll, Dan Tecuci, Wan Ching Ho and Ningxuan Wang 15:10-15:30 Exploring the space of computational memory models Nate Derbinsky and Nicholas A. Gorski	A process based on the fuzzy set theory for evaluation of link prediction methods E. Alves da Silva and M. Carvalho de Andrade Social aspects of video recording A. Basso, M. Milanesio and A. Panisson Agent-based economic modeling with finite state machines I. Gnilomedov and S. Nikolenko	ETHICAL REASONING, EMOTIONS AND QUESTION GENERATION 14:00-14:15 Political question generation method using minutes of municipal councils Yasutomo Kimura, Hideyuki Shibuki, Keiichi Takamaru, Tetsuro Kobayashi, Tatsunori Mori 14:15-14:30 Machine learning and affect analysis against cyber-bullying Michal Ptaszynski, Pawel Dybala, Tatsuaki Matsuba, Fumito Masui, Rafal Rzepka, Kenji Araki 14:30-14:45 An idea of a web-crowd based moral reasoning agent Radoslaw Komuda, Michal Ptaszynski , Rafal Rzepka, Kenji Araki 14:45-15:30 Summary and Discussion Panel	14:00-14:30 How to detect an android Antoni Diller 14:30-15:30 Workshop groups activity – Toward new test proposals
15:30			Coffee Break		

	Room 1: Mathematical Practice and Cognition	Room 2: Human Memory for Artificial Agents	Room 4: Social Network Analysis and Norms for MAS	Room 6: Linguistic and Cognitive Approaches To Dialogue Agents	Room 7: Towards a Comprehensive Intelligence Test
16:00	16:00-16:30 Where axioms come from Dirk Schlimm 16:30-17:30 — Invited talk Mathematical argumentation and the Toulmin model Brendan Larvor	MEMORY MODELS AND ALGORITHMS (CONT'D) 16:00-16:20 Forgetting and generalisation in memory modelling for robot companions: a data mining approach Patricia A. Vargas, Ruth Aylett, Mei Yii Lim, Wan Ching Ho, Sibylle Enz and Alex A. Freitas 16:20-17:30 Open discussion	The hidden path from delegation to obligations: a logical analysis E. Lorini Power laws and levels of abstraction in understanding legal systems U. Pagallo Temporal reasoning and normative MAS C. Smith, A. Rotolo and G. Sartor	16:00-17:30 — Invited talk Applying concept acquisition to dialogue generation Brandon Rohrer	16:00-17:30 Workshop groups activity – Toward new test proposals (cont'd)
17:30			Sessions end		
	Workshop Dinner (TBA)				

19:00 — Optional movie, for all convention participants, at Phoenix Square in the Leicester Cultural Quarter

Artificial Intelligence (12)

£4.80 (with DMU discount) and £3.80 (on the presentation of AISB2010 delegates badge)

	Room 1: Mathematical Practice and Cognition	Room 3: Al and Games	Room 4: Social Network Analysis and Norms for MAS	Room 5 + Theatre Room: Swarm Intelligence Algorithms and Applications	Room 7: Towards a Comprehensive Intelligence Test
8:30 9:00	9:00-10:00 — Invited talk Types of Generality in and around Mathematics and Logics Ivor Grattan-Guinness 10:00-10:30 Skills and Mathematical Knowledge Benedikt Loewe, Thomas Müller	FULL PAPERS 9:00-9:05 Welcome Daniela Romano and David Moffat 9:05-09:35 A hierarchical task network planner for pathfinding in real-time strategy games Munir Naveed, Diane Kitchin and Andrew Crampton 09:35-10:35	Introduction to NorMAS 2010 Contract argumentation in virtual organizations Criado, Heras, Argente, and Julian Norm emergence in regulatory compliance Burgemeestre, Hulstijn and Tan	9:00-9:30 From ants to robots: a decentralised task allocation model for a swarm of robots Sifat Momen & Amnada J.C. Sharkey 9:30-10:00 Application of CACS approach for distributed logistic systems Sami Al-Maqtari, Habib Abdulrab & Eduard Babkin 10:00-10:30	9:00-9:30 Don't improve the Turing Test, abandon it Drew McDermott 9:30-10:00 From the buzzing in Turing's head to machine intelligence contests Huma Shah and Kevin Warwick 10:00-10:30 The original test: it's harder than you might think Darren Abramson
10:30		A flexible bio-affective gaming interface Jorge Arroyo-Palacios and Daniela M. Romano	Coffee Break	Swarm intelligence to distribute simulations in computational ecosystems Antoine Dutot, Damien Olivier & Guilhelm Savin	

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11:00	Analogical Reasoning, Resource Allocation and Task-Engagement in Individuals Differing in Mathematical Abilities Elke van der Meer, Boris Bornemann, Jan Ries, Judith Horn, Manja Foth, Isabell Wartenburger 11:20-11:40 Singing numbers in cognitive space Martin Fischer et al. 11:40-12:00 The effects of literacy on symbolic and non-symbolic numerical magnitude processing in literate and illiterate Arabic speakers Samar Zebian & Daniel Ansari 12:00-12:30 — Informal session This is an opportunity for anyone who would like to speak informally. This may be about a PhD proposal, report on work in progress, thoughts on the workshop, etc. We will arrange this on the fly at the workshop. If you would like to speak, please arrange it with Alison, Markus or Alan prior to the session.	Al PERFORMANCE 11:00-11:30 Improving games' Al performance using grouped hierarchical level of detail David Osborne and Patrick Dickinson 11:30-12:00 Group emotion modelling and the use of middleware for virtual crowds in video-games Olivier Szymanezyk and Grzegorz Cielniak 12:00-12:30 Digital Footprints – recording bot movement and behaviour to improve Al opponents in FPS games Thomas Welsh, Alastair Hebson and David C. Moffat	Non-taking2 up as a normative behavior Saillard An analysis of norm emergence in Axelrod's Model Mahmoud, Griffiths, Keppens and Luck Modelling the social fabric for normative NPCs in MMOGs Johansson and Verhagen	Tutorial Session, in Theatre Room 11:00-12:30 Exactly solved models for collective behaviour and complex systems — Part 1 Gérard H.E. Duchamp	PANEL SESSION 11:00-11:30 Computer system that likes chess Pawel Dybala, Rafal Rzepka and Kenji Araki 11:30-12:00 Man, machine, and interpretation. Donald Davidson on Turing's test Stefan Riegelnik 12:00-12:30 Some misconceptions regarding the Turing Test Hugh Loebner
12:30			Lunch + Keynote talk (at Phoenix Square)		

	Room 1: Mathematical Practice and Cognition	Room 3: Al and Games	Room 4: Social Network Analysis and Norms for MAS	Room 5 + Theatre Room: Swarm Intelligence Algorithms and Applications	Room 7: Towards a Comprehensive Intelligence Test
14:00	14:00-14:30 Peer review and knowledge by testimony in mathematics Benedikt Loewe, Christian Geist, Bart Van Kerkhove 14:30-15:30 — Invited talk Rationale of the mathematical joke Andrew Aberdein	PLAYER MODELING 14:00-14:30 AEINS: The role of interactive narrative in fostering character education Rania Hodhod, Daniel Kudenko and Paul Cairns 14:30-15:00 Using a cognitive architecture for opponent target prediction Simon Butler and Yiannis Demiris 15:00-15:30 Towards automatic player behaviour characterisation using multiclass-linear discriminant analysis Robin Baumgarten	11:00-12:30 — Invited talk The uniqueness of normative behaviour Corinna Elsenbroich	Tutorial Session, in Theatre Room 14:00-15:30 Exactly solved models for collective behaviour and complex systems — Part 1 Gérard H.E. Duchamp	14:00 — Demo poster Have a chat with sensitive artificial listeners Marc Schröder, Sathish Pammi, Roddy Cowie, Gary McKeown, Hatice Gunes, Maja Pantic, Michel Valstar, Dirk Heylen, Mark ter Maat, Florian Eyben, Björn Schuller, Martin Wöllmer, Elisabetta Bevacqua, Catherine Pelachaud and Etienne de Sevin 14:15-14:30 — Poster A proposed replacement for the Turing Test Doug Samuelson 14:30-15:30 Report back from group activities on Monday
15:30			Coffee Break		

	Room 1: Mathematical Practice and Cognition	Room 3: Al and Games	Room 4: Social Network Analysis and Norms for MAS	Room 5 + Theatre Room: Swarm Intelligence Algorithms and Applications	Room 7: Towards a Comprehensive Intelligence Test
16:00	16:00-17:30 Panel session	DEMO AND POSTERS SESSION 16:00-16:30 (see * below for presenters) Al FOR GAME DESIGN 16:30-17:00 Procedural content generation and level design for computer games Simon Cooper, Abdennour El Rhalibi, Madjid Merabti and Jon Wetherall 17:00-17:30 Evolving pixel shaders for the prototype video game Subversion Andrew Howlett, Simon Colton and Cameron Browne	Discussion session – the future of NorMAS	Tutorial Session, in Theatre Room 16:00-17:30 — Special event Aldebaran Robotics	Panel discussion
17:30			Sessions end		

19:00 — Optional movie, for all convention participants, at Phoenix Square in the Leicester Cultural Quarter

**Breaking the Code* (12A)*

£4.80 (with DMU discount) and £3.80 (on the presentation of AISB2010 delegates badge)

Special event for all convention participants: Tutorial by Aldebaran Robotics, 16:00-17:30, in the Theatre Room

DEMO: Digital Footprints -- a tool for generating heat maps and capturing data from FPS games Alastair Hebson, Thomas Welsh and David C. Moffat

POSTER: EDEE: a flexible environment for research Ningxuan Wang, Christopher Cullen and Andrew Nuxoll

POSTER: A design and implementation of 3D image interactive vision system Sang Heon Han, Chang Ok Yun, Jung hoon Kim, Jae Ik Jo, Tae Soo Yun & Dong Hoon Lee

POSTER: Distributed drama management: integrating levels of narrative responsibility Allan Weallans and Sandy Louchart

POSTER: Towards the use of trait inheritance for flocks of navigating agents Piotr Piasecki and Christopher Peters

POSTER: Towards a Goal Oriented Action Planning Approach for predator-prey simulation Justyna Pultowicz and Christopher Peters

^{*} Demos and Posters for Al and Games, 16:00-16:30:

	Room 1: Biologically inspired AI vs AI inspired Biology	Room 2: New Frontiers in Human-Robot Interaction	Room 4: Matching and Meaning	Room 5: Evolving Intelligent Systems
8:30		Regis	stration	
9:00	8:45- 09:00 General introduction and welcome Jackie Chappell (Chair) 9:00-09:45 The design-based approach to the study of mind Aaron Sloman 9:45-10:30 Al-inspired biology: does Al have something to contribute to biology? Jackie Chappell and Susannah Thorpe	9:00-9:05 Opening and welcome MULTI-MODAL HUMAN-ROBOT INTERACTION 9:05-9:20 Expressive gestures displayed by a humanoid robot during a storytelling application Catherine Pelachaud, Rodolphe Gelin, Jean-Claude Martin and Quoc Anh Le 9:20-9:35 Mirror my emotions! Combining facial expression analysis and synthesis on a robot Stefan Sosnowski, Christoph Mayer, Kolja Kühnlenz and Bernd Radig 9:35-9:50 Reducing speech collisions by using an artificial subtle expression in a decelerated spoken dialogue — Should communication robots respond quickly? Kotaro Funakoshi, Kazuki Kobayashi, Mikio Nakano, Takanori Komatsu and Seiji Yamada 9:50-10:05 Evaluation of robot body movements supporting communication Helge Hüttenrauch, Cristian Bogdan, Anders Green, Kerstin Severinson Eklundh, Dominik Ertl, Jürgen Falb, Hermann Kaindl, Michael Göller 10:05-10:30 Discussion	9:30-10:30 — Invited talk Alan Bundy	8:45- 09:00 Opening address EIS METHODOLOGY 1 A structure evolved learning method for Mamdani fuzzy systems Di Wang, Xiao-Jun Zeng and John Keane Dynamic analysis of the participatory learning algorithm Elton Lima, Rosangela Ballini, Fernando Gomide The need for benchmarks and meta-models in evolving systems Katharina Tschumitschew and Frank Klawonn
10.50		Colle	E DIEAK	

	Room 1: Biologically inspired AI vs AI inspired Biology	Room 2: New Frontiers in Human-Robot Interaction	Room 4: Matching and Meaning	Room 5: Evolving Intelligent Systems
11:00	11:00-11:45 Why can't we build robots that are as clever as crows? Murray Shanahan 11:45-12:15 The logic of robotics inspired biology Martin Hülse and Mark Lee 12:15-12:30 2-minute poster announcements	DESIGN PERSPECTIVES 11.00-11.15 On making robots invisible-in-use Leila Takayama 11:15-11:25 Discussion 11.25-12.05 — Keynote talk Expressive robots and expressive interaction with robots: a design perspective Patrizia Marti 12:05-12:30 Discussion	11:00-11:30 Automatizing the evaluation of model matching systems Kelly Garces, Wolfgang Kling and Frederic Jouault 11:30-12:00 Recommendations for better quality ontology matching evaluations Aliaksandr Autayeu, Vincenzo Maltese and Pierre Andrews 12:00-12:30 The role of taxonomy properties in information content metrics Raul Ernesto Menendez-Mora and Ryutaro Ichise	EIS METHODOLOGY 2 Cascaded multi-resolution spline-based fuzzy neural network Vitaliy Kolodyazhniy and Yevgeniy Bodyanskiy Clustering as a tool for self-generation of intelligent systems: a survey Rashmi Dutta Baruah and Plamen Angelov Reactive-adaptive methodology to encode evolving intelligent agents in serious games Mario Gongora and David Irvine Lifelong learning by evolution in robotics: bridging the gap from theory to reality Borja Santos-Diez, Fran-cisco Bellas, Andres Faina and Richard Duro
12:30	Lunch + Keynote talk (at Phoenix Square)			

	Room 1: Biologically inspired AI vs AI inspired Biology	Room 2: New Frontiers in Human-Robot Interaction	Room 4: Matching and Meaning	Room 5: Evolving Intelligent Systems
14:00	14:00-14:45 The role of vision and attention in language processing Antje Meyer 14:45-15:15 Constructing emotions: epistemological groundings and robotics' applications for a synthetic approach to emotions Luisa Damiano and Lola Cañamero 15:15-15:30 Discussion session	DESIGN AND ANALYSIS OF HUMAN-ROBOT INTERACTION 14:00-14:15 Social, functional, and problem-related tasks in HRI - a comparative analysis of body orientation and gaze Manja Lohse 14:15-14:30 Validating characterizations of sociality in HRI: the case of interaction patterns Peter H. Kahn, Jr., Brian T. Gill, Aimee L. Reichert, Takayuki Kanda, Hiroshi Ishiguro and Jolina H. Ruckert 14:30-14:45 Development of human-robot interaction models by means of a cognitive walkthrough approach Astrid Weiss, Florian Foerster, Daniela Wurhofer and Manfred Tscheligi 14:45-15:00 Exploratory analysis of operator: robot ratio in search and rescue missions Alberto Valero, Chiara Saracini, Paloma de la Puente, Diego Rodriguez- Losada, Fernando Matia 15:00-15:30 Discussion	Poster Talks 14:00-14:10 An evidence based approach to collaborative ontology development Emma Tonkin, Heather D. Pfeiffer and Andrew Hewson 14:10-14:20 Evaluation of error taxonomy for OWL2 Naseer Ahmed Sajid and Muhammad Abdul Qadir 14:20-14:30 A framework for mapping refinement specification Faycal Hamdi, Chantal Reynaud and Brigitte Safar Poster Session 14:30-15:30	Rew developments in statistical signal processing of quaternion random variables with applications in wind forecasting Clive Cheong Took and Danilo P. Mandic Application of ANN-GA hybrid to run a conveyor control system Paul Morley and Jeff Johnson An evolving framework for clustering computer users Jose Iglesias, Agapito Le-dezma and Araceli Sanchis
15:30	Coffee Break			

	Room 1: Biologically inspired AI vs AI inspired Biology	Room 2: New Frontiers in Human-Robot Interaction	Room 4: Matching and Meaning	Room 5: Evolving Intelligent Systems
16:00	16:00-16:45 Biological and cultural foundations of human language: insights from computer simulations Nick Chater 16:45-17:15 Al, attachment theory and simulating secure base behaviour: Dr. Bowlby meet the Reverend Bayes Dean Petters and Everett Waters 17:15-18:00 Discussion	ROBOSKIN - ARTIFICIAL SKIN FOR HUMANOID ROBOTS 16:00-16:15 Touch-Triggered Protective Reflexes for Safer Robots Torbjørn S. Dahl and Andrew Palmer 16:15-16:30 Policy Adaptation through Tactile Correction Brenna D. Argall, Eric L. Sauser and Aude G. Billard 16:30-16:45 Towards Intrinsically Learned Skin Models in Robots Simon McGregor and Daniel Polani 16:45-17:00 Towards a Skin-Like Embedded Tactile Sensor for Robotic Hands Andrea Biggio, Perla Maiolino and Giorgio Cannata 17:00-17:30 Discussion	Representation and reasoning for ontology evolution Michael Chan, Alan Bundy and Jos Lehmann 16:30-17:00 Studying concept shift in political ontologies Shenghui Wang, Stefan Schlobach, Janet Takens and Wouter van Atteveldt	An online predictor model as adaptive linear model and evolving Takagi-Sugeno model Ahmad Kalhor, Babak N. Araabi and Caro Lucas Incremental classification of images by human assisted fuzzy similarity analysis Gancho Vachkov Clustering to train an evolving radial basis function Jose de Jesus Rubio, Jaime Pacheco and Raul Rivera
17:30	Session end	Session end	Session end	17:30-17:45 Closing and round up
18:00			Workshop drinks (venue TBA)	
19:00	Convention Dinner At Belmont Hotel • De Montfort Street • Leicester • LE1 7GR			

19:00 — Optional movie, for all convention participants, at Phoenix Square in the Leicester Cultural Quarter

Moon (15)

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Detailed Programme: THURSDAY 1st April

	Room 1: Biologically inspired AI vs AI inspired Biology	Room 2: New Frontiers in Human-Robot Interaction	Room 4: Matching and Meaning
8:30		Registration	_
9:00	9:00-9:45 Social cognition: views from developmental and comparative psychology, and robotics on the role of emotion in joint attention Kim A. Bard 9:45-10:15 Advancing knowledge of cognitive development sequences in infancy Frank Guerin 10:15-10:30 Discussion session	9:00-9:15 Towards HRI on the move with mixed initiative Cristian Bogdan, Dominik Ertl, Michael Göller, Anders Green and Kerstin Severinson Eklundh 9:15-9:30 A smart action selection architecture taking into account both goal-orientedness and proactivity Woo Young Kwon and II Hong Suh 9:30-9:45 An autonomous proxemic system for a mobile companion robot Mohammadreza Asghari Oskoei, Michael L. Walters and Kerstin Dautenhahn 9:45-10:00 Robot learning of lexical semantics from sensorimotor interaction and the unrestricted speech of human tutors Joe Saunders, Chrystopher L. Nehaniv and Caroline Lyon 10:00-10:30 Discussion	09:30-10:00 Adaptive user interface assistance in smart environments Maximilian Kern, Frank Trollmann, Marco Blumendorf and Sahin Albayrak 10:00-10:30 An approach for bipolar ontology alignment argumentation in multi-agent systems Paulo Maio and Nuno Silva
10:30		Coffee Break	

Detailed Programme: THURSDAY 1st April

	Room 1: Biologically inspired AI vs AI inspired Biology	Room 2: New Frontiers in Human-Robot Interaction	Room 4: Matching and Meaning
11:00	11:00-11:30 Modeling visual affordances: the selective attention for action model (SAAM) Christoph Böhme and Dietmar Heinke 11:30-12:00 Route learning through classification Bart Baddeley, Paul Graham, Andrew Philippides and Philip Husbands 12:00-12:30 Demonstration (Possibly involving Nick Hawes, Susannah Thorpe and Michael Zillich)	ATTITUDES AND RELATIONSHIPS WITH ROBOTS 11:00-11:15 Ibn Sina steps out: exploring Arabic attitudes toward humanoid robots Laurel D. Riek, Nikolaos Mavridis, Shammah Antali, Noura Darmaki, Zeeshan Ahmed, Maitha Al-Neyadi and Amina Alketheri 11:15-11:25 Discussion 11:25-12:10 — Keynote talk Is a Companion a distinctive kind of relationship with a machine? Yorick Wilks 12:10-12:30 Discussion	11:00-12:30 — Panel session Jos Lehmann, Vincenzo Maltese, and Fiona McNeill
12:30		Lunch + Keynote talk (at Phoenix Square)	

Detailed Programme: THURSDAY 1st April

	Room 1: Biologically inspired AI vs AI inspired Biology	Room 2: New Frontiers in Human-Robot Interaction	Room 4: Matching and Meaning
14:00	14:00-14:45 Forward and inverse models in motor control and cognitive control Richard P. Cooper 14:45-15:30 The adaptive nature of reward: a computational framework for understanding intrinsic motivation Richard L. Lewis, Satinder Singh and Andrew Barto	ROBOTS FOR THE YOUNG AND OLD 14:00-14:20 A robot as persuasive social actor: a field trial on child-robot interaction Astrid Weiss, Thomas Scherndl, Roland Buchner and Manfred Tscheligi 14:20-14:40 How infants perceive the toy robot Pleo. An exploratory case study on infant-robot-interaction Karola Pitsch and Benjamin Koch 14:40-15:00 Ethical issues in robot care for the elderly: Dystopia or optimism? Amanda Sharkey and Noel Sharkey 15:00-15:30 Discussion	14:00-14:30 Exploring ontology merging with examples Liwei Deng 14:30-15:00 Integrating technical terms into Thesaurus using extracted related words Yoshimi Suzuki and Fumiyo Fukumoto 15:00 Close of workshop
15:30		Coffee Break	
16:00	16:00-16:45 Causal networks in neural systems: from brain-based devices to consciousness Anil Seth 16:50-18:00 Concluding discussion session Introduced by Margaret Boden	16:00-17:00 — Panel How social do robots really need to be? Panel members include Laurel Riek, Amanda Sharkey, Astrid Weiss, Karola Pitsch, Leila Takayama, Yorick Wilks. Chaired by Kerstin Dautenhahn 17:00-17:30 Final discussion and conclusion	
17:30		Sessions end	

19:00 — Optional movie, for all convention participants, at Phoenix Square in the Leicester Cultural Quarter Bicentennial Man (15) [To be confirmed]

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